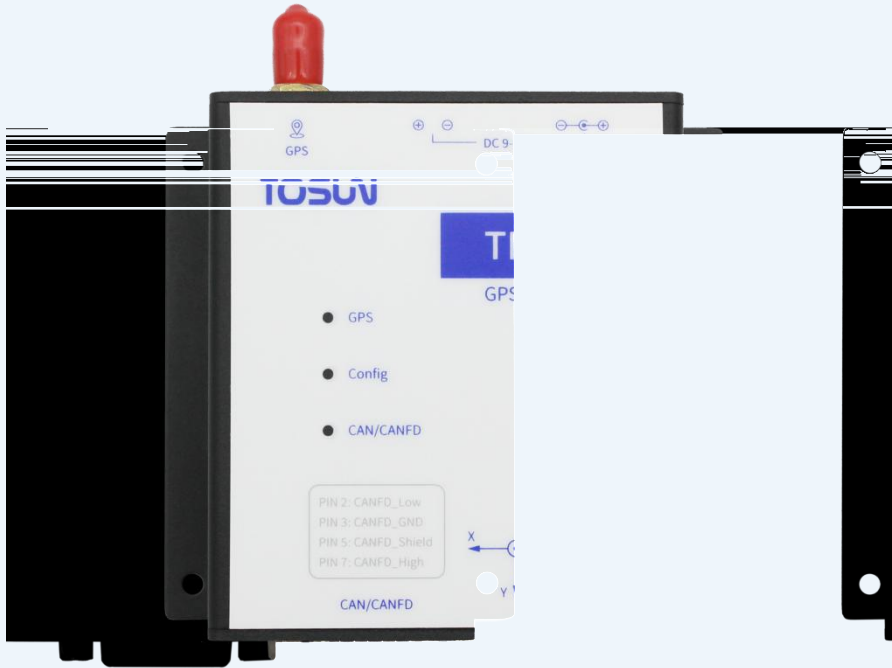


TOSUN



70 3URGXFWD0DQXDC

WRVXQDL FRP

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:K\ ,V D - *30\$1 'HYLFH 1HFHVVDU\

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: K D W & D Ø 0 W K H' R

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\$ERXW WKLV 8VHU 0DQXDO

:DUUDQW\

&RS\ULJKW

70

2YHUYLHZ

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)HDWXUHV

- ✓
- ✓
- ✓
- ✓
- ✓
- ✓
- ✓

7HFKQLFDO 'DWD

✓

	- -
	-
	- ~
	~ (non-condensing)

✓

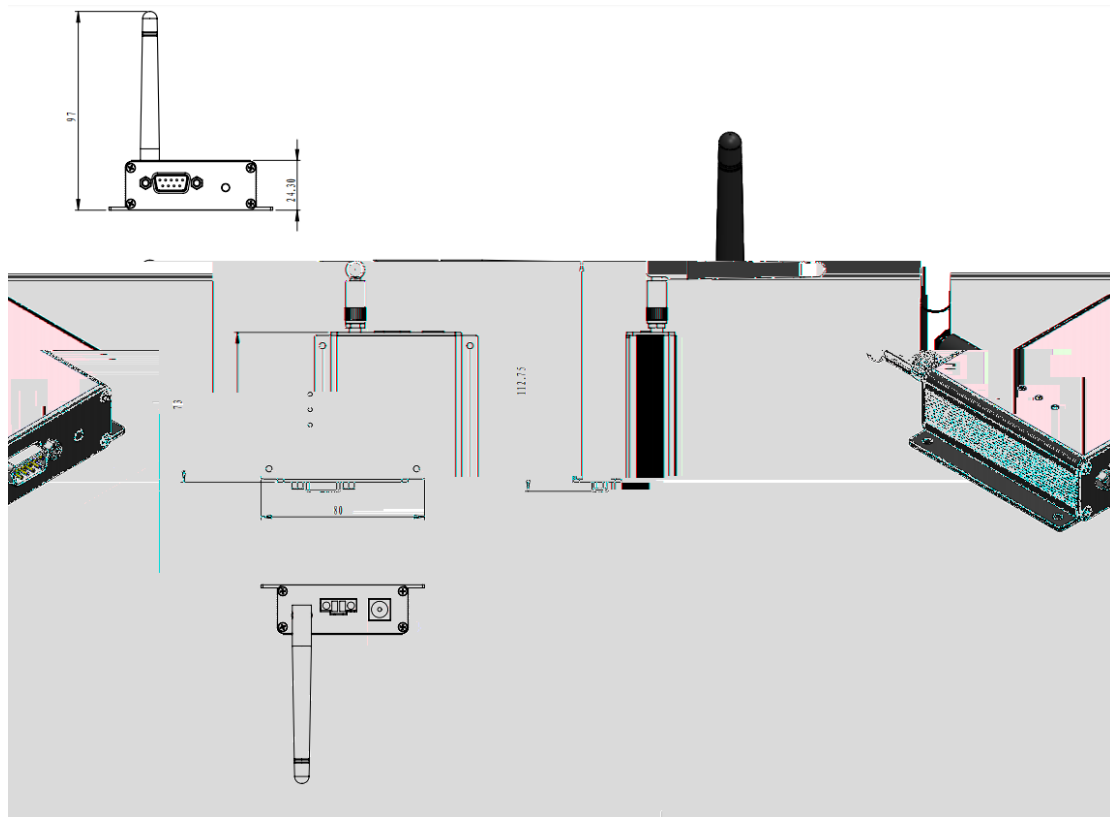
✓

(OHFWULFD O 'DWD

		Test Condition	Minimum Value	Typical Value		
	External DC power supply	CAN transmission				
	External DC power supply	CAN transmission	--		--	
	External DC power supply	CAN transmission	--		--	

Bus pin
 voltage
 CAN
 Interface resistance

0HFKDQLFDO 'DWD



6FRSH RI 'HOLYHU\

✓

✓



✓

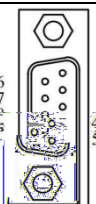


+DUGZDUH ,QWHUIDFH



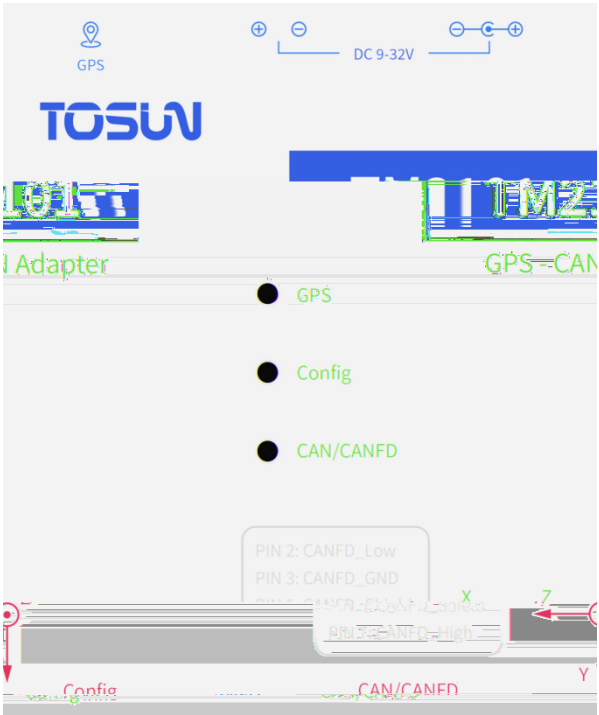
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' % 3 L	3 , 1	' H I L Q L W L
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	1 X P E H	
		

1 (

✓



✓

, Q G L F D \	' H I L Q L W L R Q
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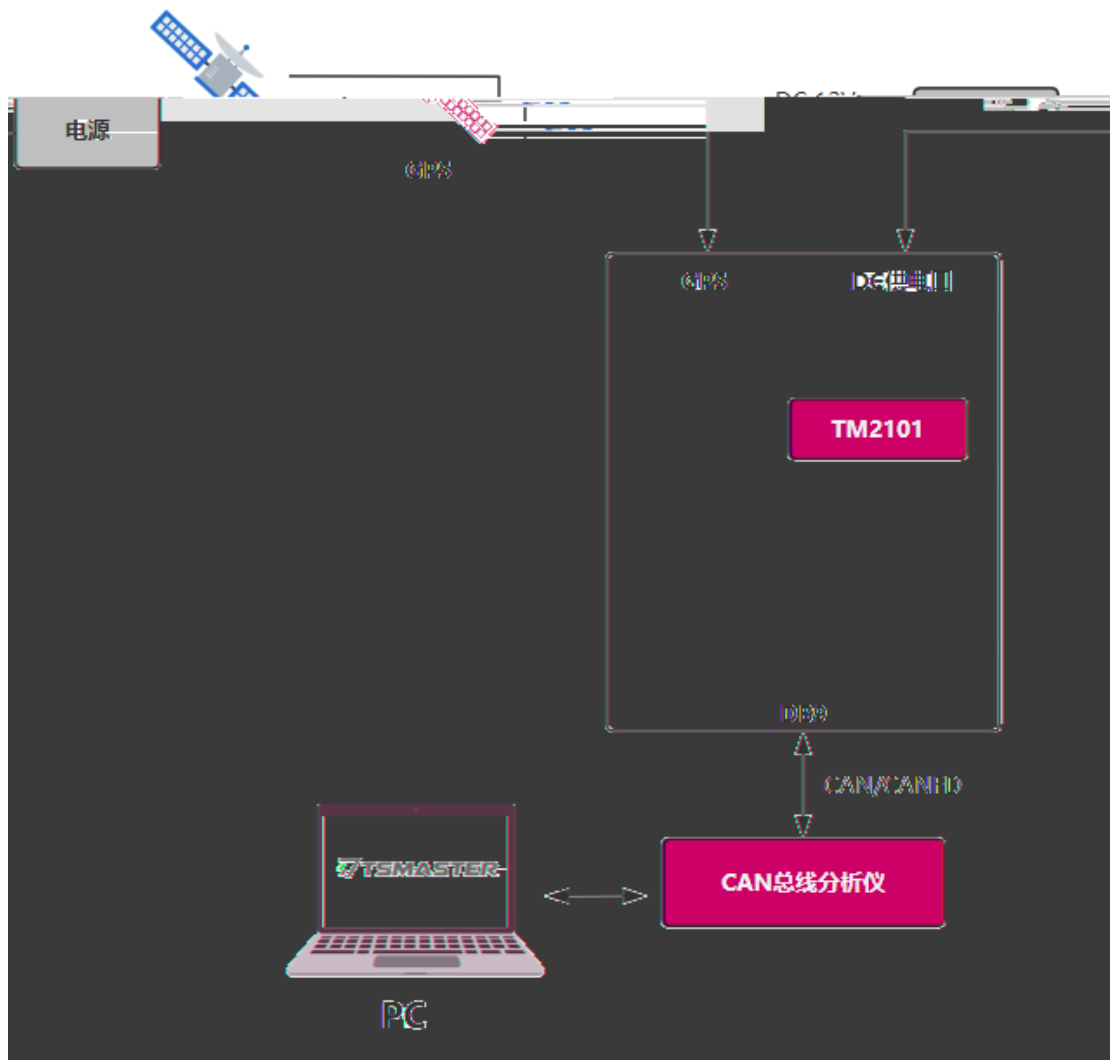
✓

, Q G L F D W	' H V F U L S W L R Q
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2SWLRQDO \$FFHVVRULHV

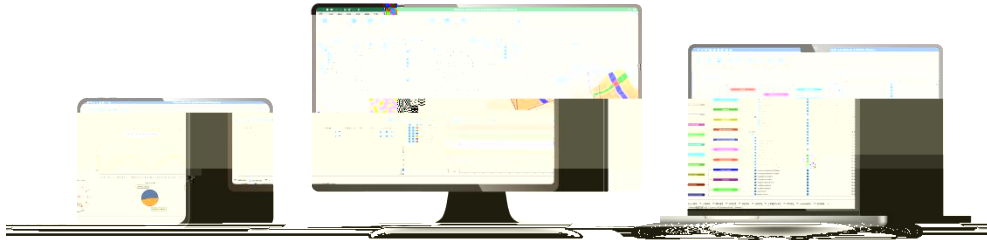
4XLFN 6WDUW

6\ VWHP & RQQHFWLRQ

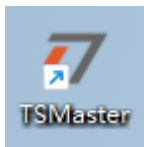


'ULYHU ,QVWDOODWLRQ

6RIWZDUH 2YHUYLHZ



6RIWZDUH ,QVWDOODWLRQ



)XQFWDRGXOH

)XOPRGH 3RVLWLRQLQJ DQG 1DYLJDWLRQ ORGXOH

-

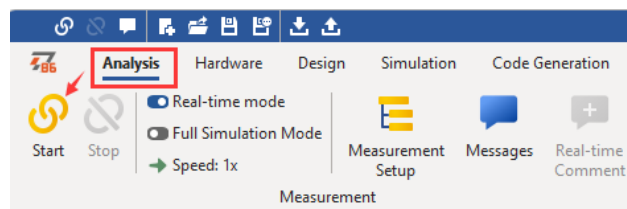
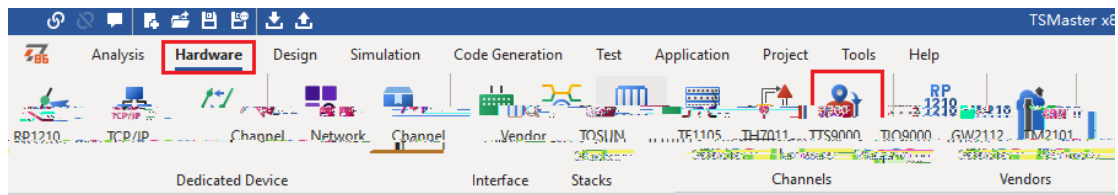
-

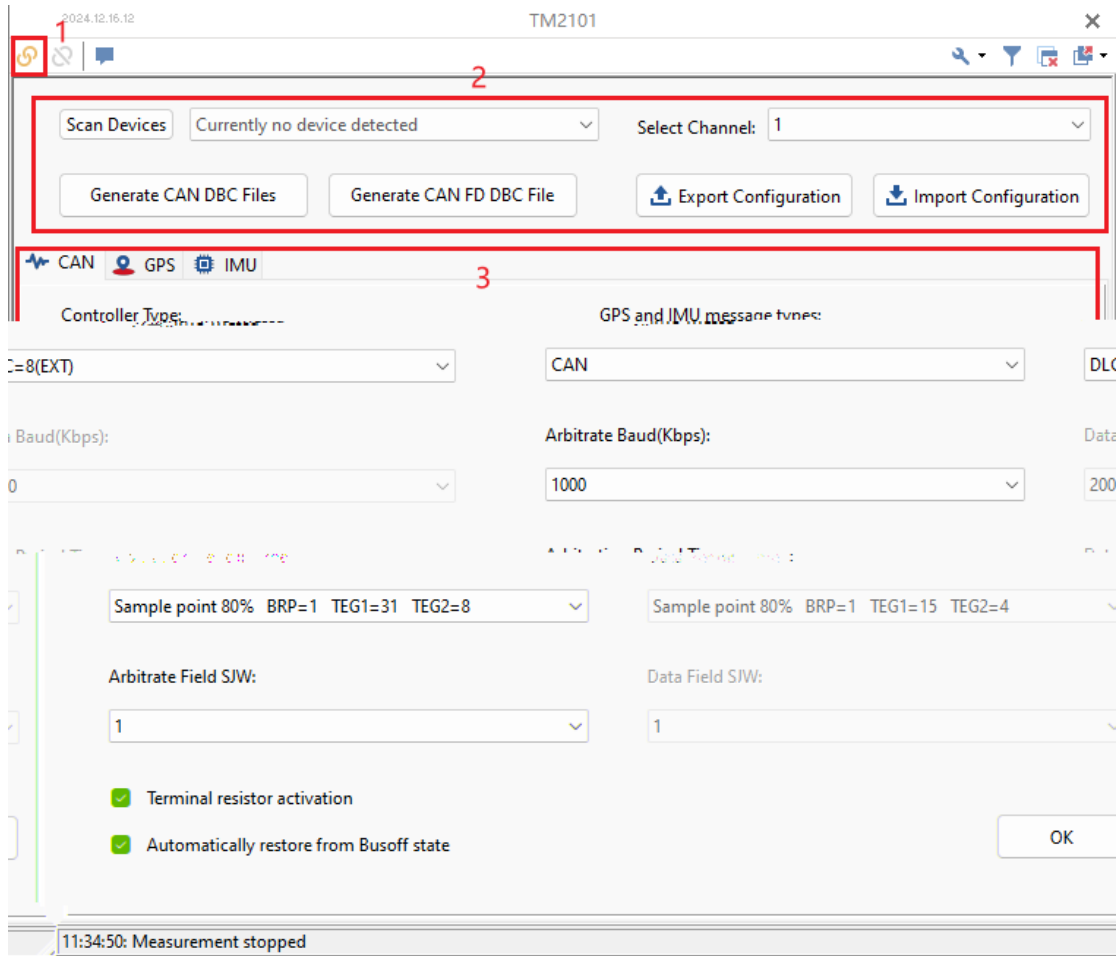
*\URVFRSH DQG \$FFHOHURPHWHU

-

)XQGDPHQWDO 8VDJH

%DVLF ,QWURGXFWRQ





(1)

(2)



(1)

(2)

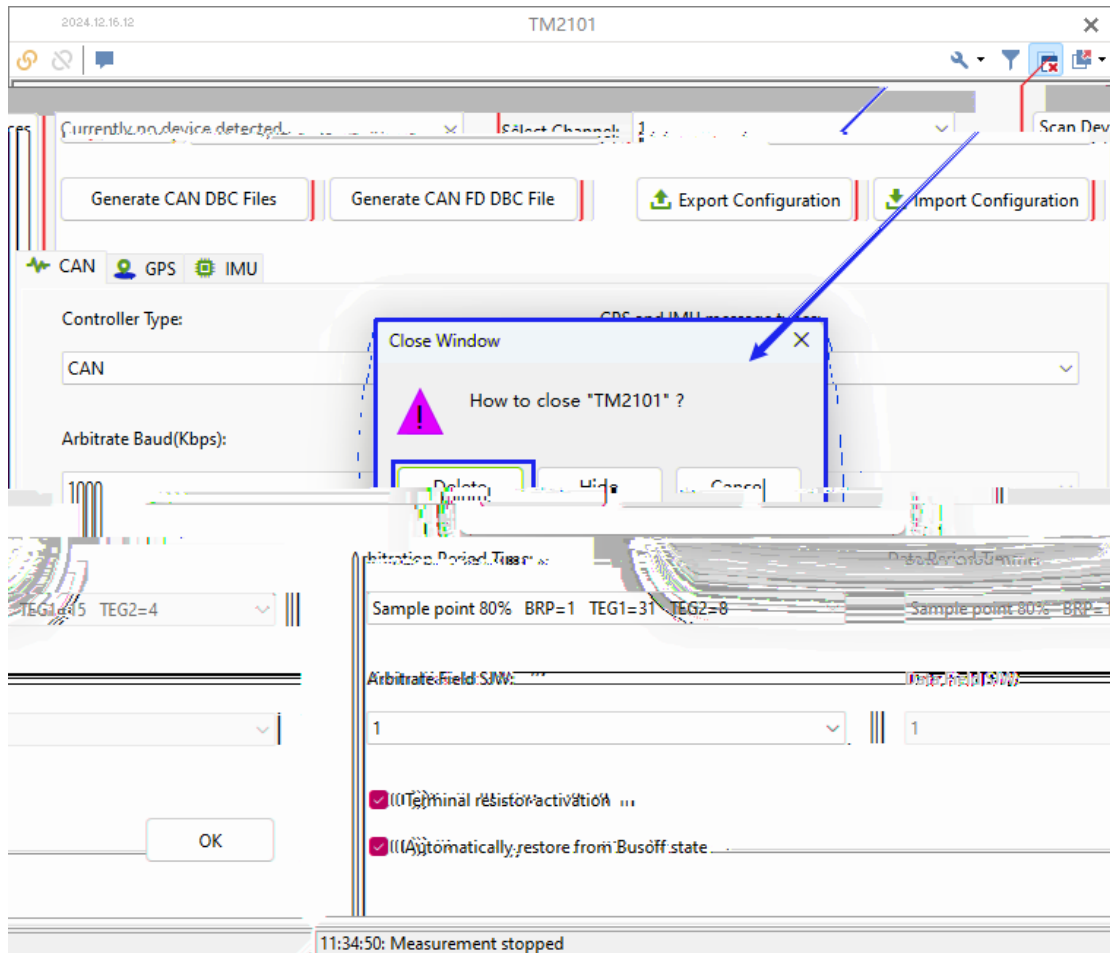
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(1)

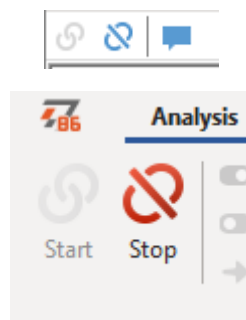
(2)

(3)

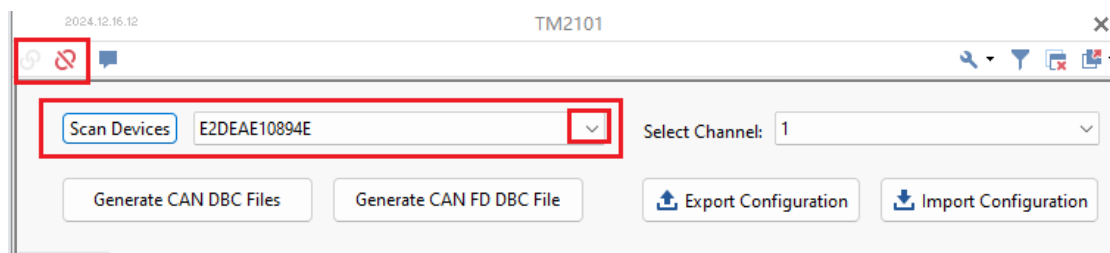
'HWDLQWGRGXFWLRQ

◆

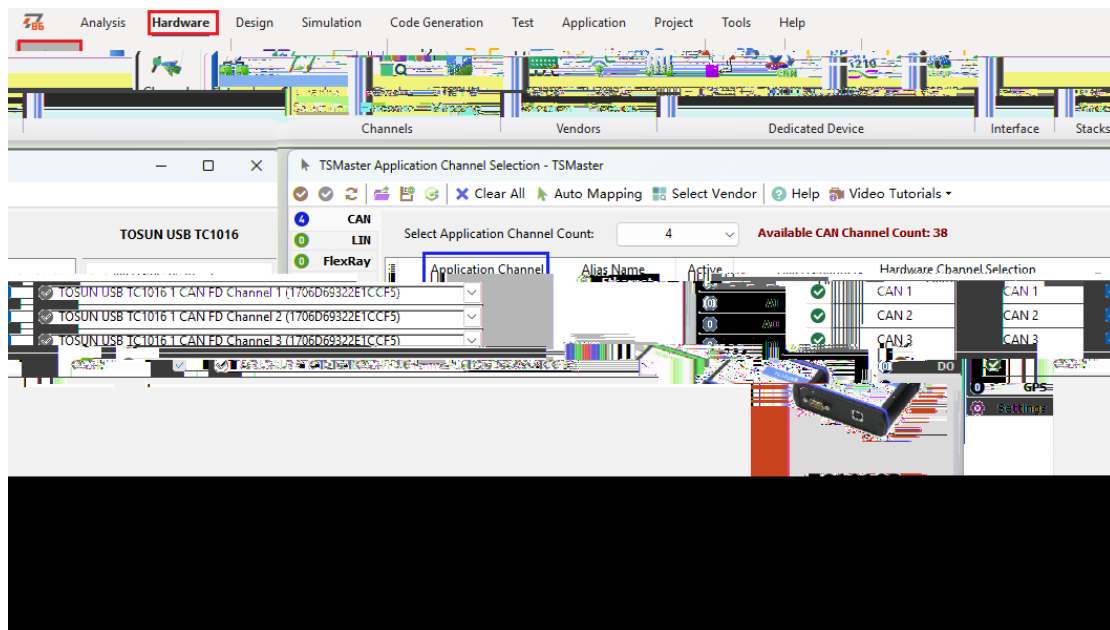
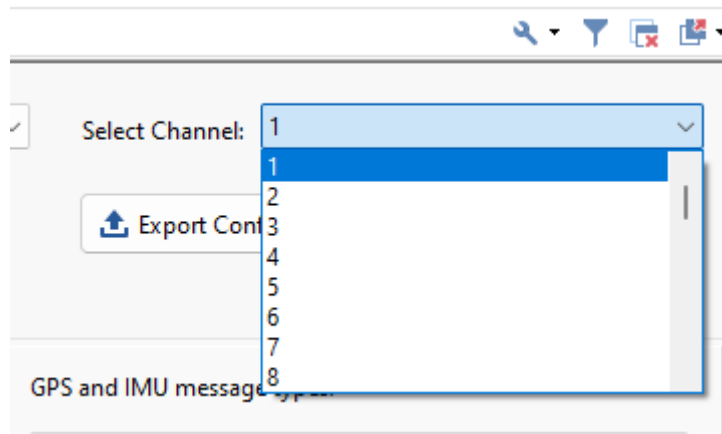
(1)



(2)



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CAN
GPS
IMU

Controller Type:
CAN

GPS and IMU message types:
DLC=8(EXT)

Arbitrate Baud(Kbps):
1000

Data Baud(Kbps):
2000

Arbitration Period Time:
Sample point 80% BRP=1 TEG1=31 TEG2=8

Data Period Time:
Sample point 80% BRP=1 TEG1=15 TEG2=4

Arbitrate Field SJW:
1

Data Field SJW:
1

☒ Terminal resistor activation
☒ Automatically restore from Busoff state

OK

GPS and IMU message types:

DLC=8(EXT)
DLC=8(STD)
DLC=8(EXT)

CAN

GPS

IMU

Controller Type:

GPS and IMU message types:

CAN FD

DLC=15(EXT)

Arbitrate Baud(Kbps):

Data Baud(Kbps):

2000

1000

Time:

Arbitration Period Time:

Data Period

int 80% BRP=1 TEG1=15 TEG2=4

Sample point 80% BRP=1 TEG1=31 TEG2=8

Sample po

JW:

Arbitrate Field SJW:

Data Field S

1

1

OK

☒ Terminal resistor activation
☒ Automatically restore from Busoff state

GPS and IMU message types:

DLC=15(EXT)

DLC=8(STD)

DLC=8(EXT)

DLC=15(STD)

DLC=15(EXT)

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(3)

(4)

CAN

GPS

IMU

Select NMEA statement:

☒ GGA
 ☐ GLL
 ☐ GSA

☐ ZDA
 ☐ DHV
 ☐ GST

GPS Data Reporting Cycle(ms):

1000

Choose a positioning satellite system:

☐ GPS
 ☒ BDS
 ☐ GLONASS

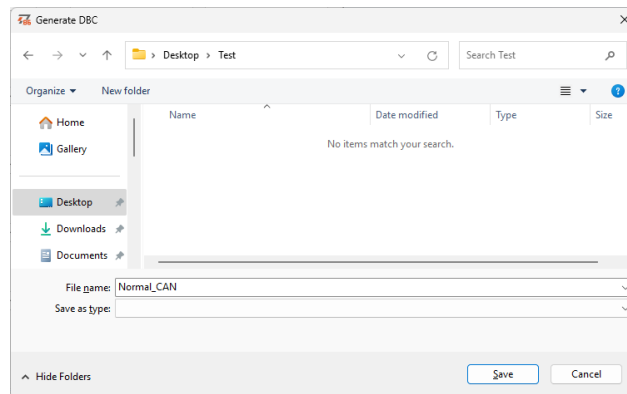
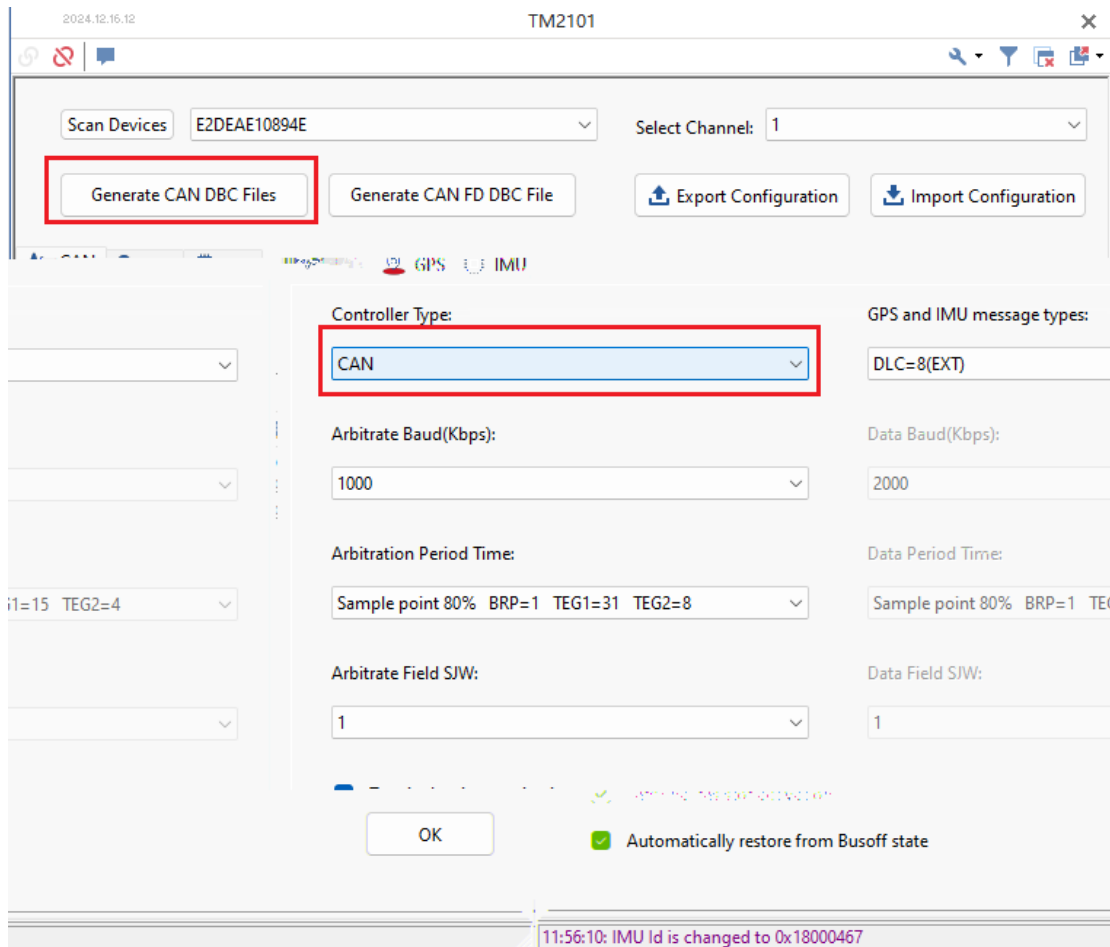
GPS data reporting ID:

0x18000464

OK

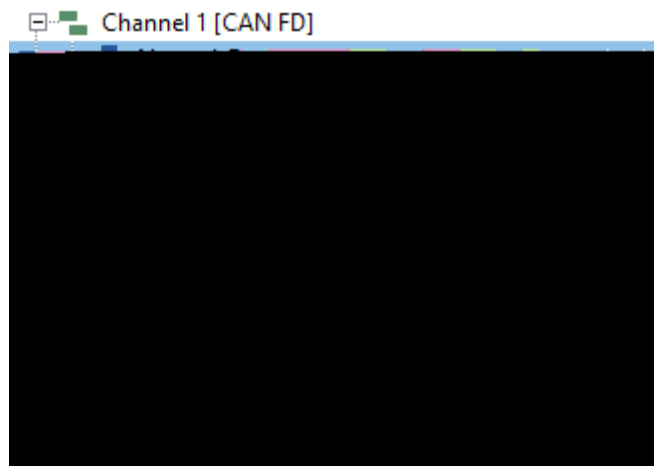
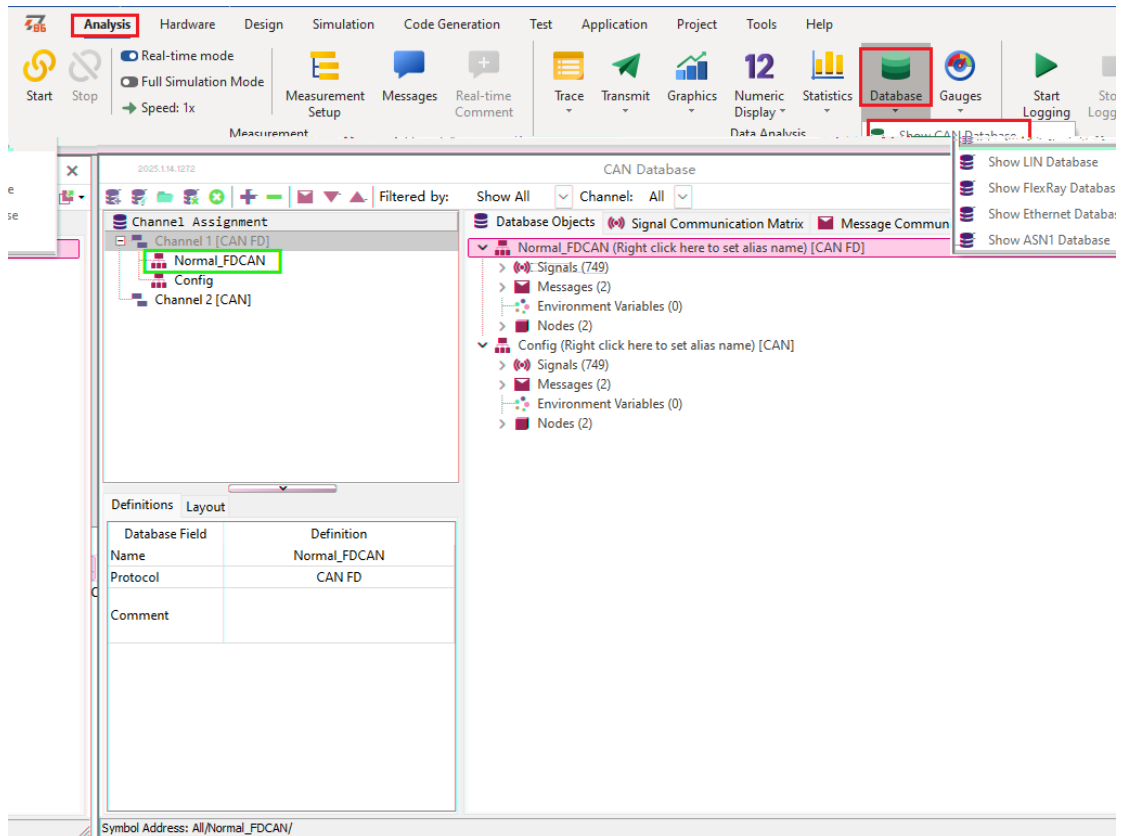
- ◆
- (1)
- (2)
- (3)
- (4)



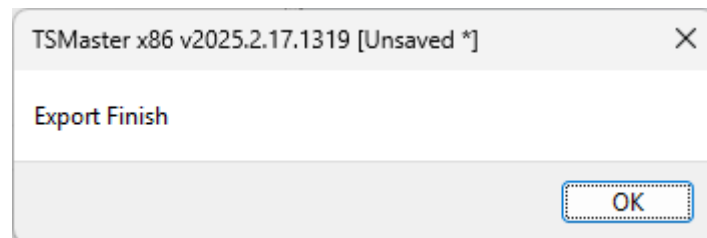
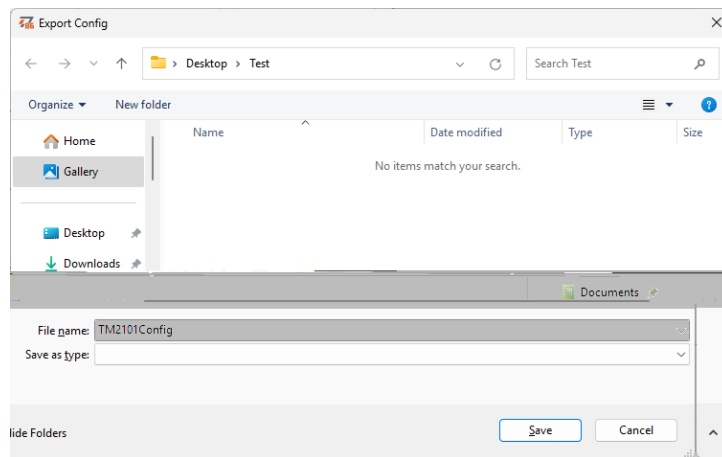


(2)

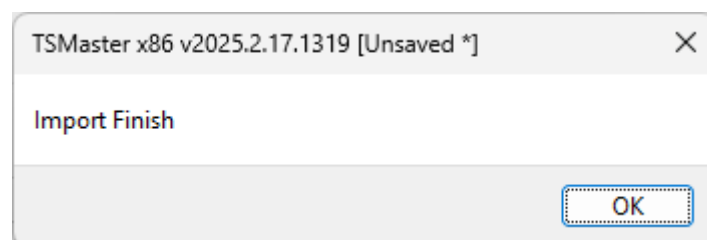
(3)



(1)



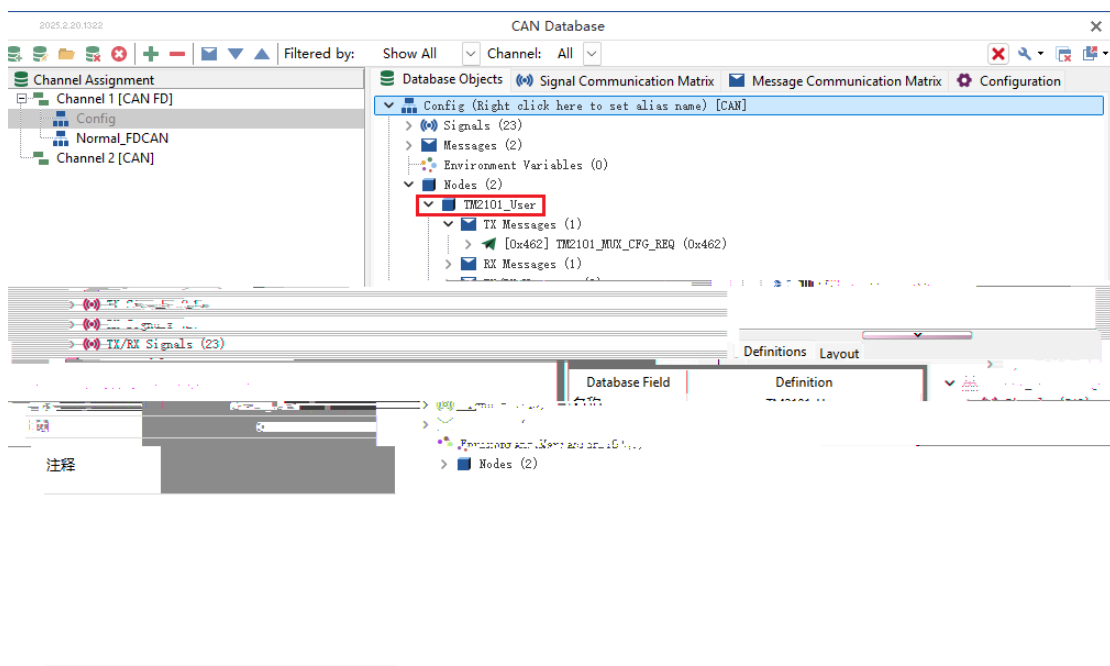
(2)



0HVVDJH 3DUVLQJ

'%&LOH 'HVFULSWLRQ

Config.dbc
Normal_bxCAN.dbc
Normal_FDCAN.dbc



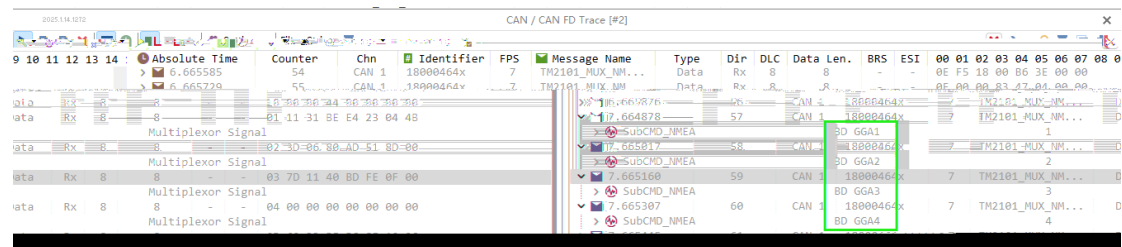


(2)

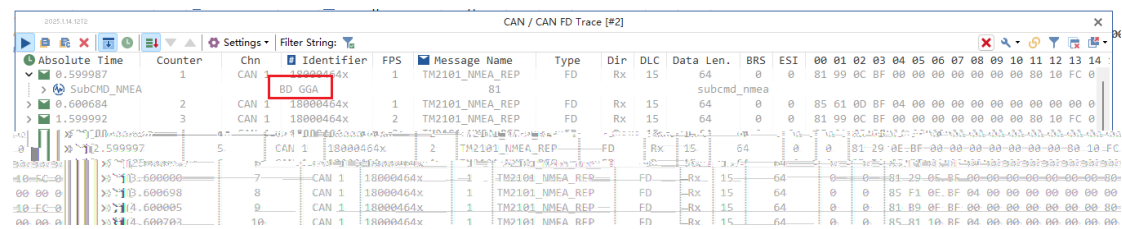
(3)

Counter	Chn	Identifier	FPS	Message Name	Type	Dir	DLC	Data Len.	BRS	ESI	Data
160	C...	18000464x	8	T212101_NMEA_REP	Data	Rx	8	8	-	-	00 01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16 17 18 19 20 21 22
152	C...	18000463x	2	T212101_IMU_REP	Data	Rx	8	8	-	-	03 03 EE FF FF FF 01 00

(2)



(3)



'H V F U L S W O L 8 R Q W R D I & \$ W 1 R



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'HVFULRW3LRQH QWHQH WR &\$1

* 3 6 6 X E 2 4 0 H U Y L H Z

#	Identifier	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14
18000464x	81	41	23	BF	04	23	04	4B	0F	06	80	AD	F1	14	6	
18000464x	85	41	23	BF	1C	8C	10	2C	3D	18	00	B6	0E	00	0	
18000464x	81	41	23	BF	04	23	04	4B	0F	06	80	AD	F1	14	6	
18000464x	85	41	23	BF	1C	8C	10	2C	3D	18	00	B6	0E	00	0	

[illegible]

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* / Ø H V V D J H



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(3)

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9 70*HVVDJH



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= '\$HVVDJH



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'+0HVVDJH



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8 70&H V V D J H



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(2)



* 607H V V D J H



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	-							



,QVSHFWLRQ DQG ODLQWHQDQFH

	humidity. (Including the internal humidity of enclosed environments)	humidity must be within the range of 10% to 90%	the humidity and ensure that the ambient humidity within the acceptable range.
	Check for the accumulation of dust, powder, salt, and metal shavings	No accumulation	Clean and protect the equipment.
	Check for any contact with water, oil, or chemical sprays on the equipment	No contact	Clean and protect the equipment if necessary.
	Check for the presence of corrosive or flammable gases in the equipment area	No presence	Inspect by the smell, or using a sensor.
	Check for levels of vibration and shock	Vibration and shock are within the acceptable range	Install padding or other shock-absorbing devices if necessary.
	Check for noise sources near the equipment	No significant noise source	Isolate the equipment from noise sources or protect the equipment.
Wiring Installation	Check the crimped connectors in the external wiring	Ensure enough space between the connectors	Visually inspect and adjust if necessary.
	Check for damage in the external wiring	No damage	Visually inspect and replace the wiring if necessary.

Software

Hardware

12/4/8/12-channel CAN FD/CAN to USB/PCIe device

1/2/6-channel LIN to USB/PCIe device

Multi-channel FlexRay/CAN FD to USB/PCIe device

Encrypted release, logging and bus replay

Physical programming / Residual bus simulation

Stand Python scripting

Support CAN FD and legacy SAE J2284 node

J2534 compliance / ecu flashing / OBD/VEP calibration

ECU Red code generation / Application

Multi channel automotive Ethernet / CAN FD to USB/PCIe device

Automotive Ethernet media conversion device (T1 to Tx)

Multi-channel CAN FD/Ethernet/LIN data logger